M79 Towing winch emergency release systems

(Oct 2018)

Scope

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1.1 This UR defines minimum safety standards for winch emergency release systems provided on towing winches that are used on towing ships within close quarters, ports or terminals.

1.2 This UR is not intended to cover towing winches on board ships used solely for long distance ocean towage, anchor handling or similar offshore activities.

Definitions

'Emergency release system' refers to the mechanism and associated control arrangements that are used to release the load on the towline in a controlled manner under both normal and dead-ship conditions.

'Maximum design load' is the maximum load that can be held by the winch as defined by the manufacturer (the manufacturer's rating).

'**Girting**' means the capsize of a tug when in the act of towage as a result of the towline force acting transversely to the tug (in beam direction) as a consequence of an unexpected event (could be loss of propulsion/steering or otherwise), whereby the resulting couple generated by offset and opposing transverse forces (towline force is opposed by thrust or hull resistance force) causes the tug to heel and, ultimately, to capsize. This may also be referred to as 'girthing, 'girding' or 'tripping'. See Figure 1 which shows the forces acting during towage operations.

Note:

1. This UR is to be uniformly implemented by IACS Societies for vessels contracted for construction on or after 1 January 2020.

2. The "contracted for construction" date means the date on which the contract to build the vessel is signed between the prospective owner and the shipbuilder. For further details regarding the date of "contract for construction", refer to IACS Procedural Requirement (PR) No. 29.

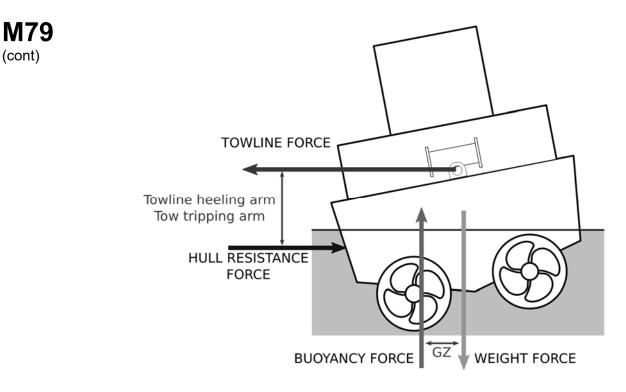
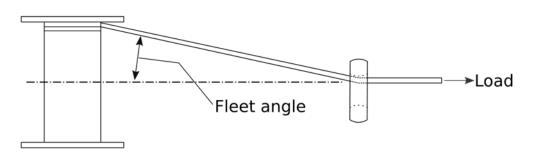


Figure 1: Forces during towing

'Fleet angle' is the angle between the applied load (towline force) and the towline as it is wound onto the winch drum, see Figure 2.





2 General requirements

2.1 The in-board end of the towline is to be attached to the winch drum with a weak link or similar arrangement that is designed to release the towline at low load.

2.2 All towing winches are to be fitted with an emergency release system.

3 Emergency release system requirements

3.1 **Performance requirements**

3.1.1 The emergency release system is to operate across the full range of towline load, fleet angle and ship heel angle under all normal and reasonably foreseeable abnormal conditions (these may include, but are not limited to, the following: vessel electrical failure, variable towline load (for example due to heavy weather), etc.).

M79 3.1.2 The emergency release system shall be capable of operating with towline loads up to at least 100 per cent of the maximum design load.

3.1.3 The emergency release system is to function as quickly as is reasonably practicable and within a maximum of three seconds after activation.

3.1.4 The emergency release system is to allow the winch drum to rotate and the towline to pay out in a controlled manner such that, when the emergency release system is activated, there is sufficient resistance to rotation to avoid uncontrolled unwinding of the towline from the drum. Spinning (free, uncontrolled rotation) of the winch drum is to be avoided, as this could cause the towline to get stuck and disable the release function of the winch.

3.1.5 Once the emergency release is activated, the towline load required to rotate the winch drum is to be no greater than:

- (a) the lesser of five tonnes or five per cent of the maximum design load when two layers of towline are on the drum, or
- (b) 15 per cent of the maximum design load where it is demonstrated that this resistance to rotation does not exceed 25 per cent of the force that will result in listing sufficient for the immersion of the lowest unprotected opening.

3.1.6 An alternative source of energy is to be provided such that normal operation of the emergency release system can be sustained under dead-ship conditions.

3.1.7 The alternative source of energy required by 3.1.6 is to be sufficient to achieve the most onerous of the following conditions (as applicable):

- (a) sufficient for at least three attempts to release the towline (i.e. three activations of the emergency release system). Where the system provides energy for more than one winch it is to be sufficient for three activations of the most demanding winch connected to it.
- (b) Where the winch design is such that the drum release mechanism requires continuous application of power (e.g. where the brake is applied by spring tension and released using hydraulic or pneumatic power) sufficient power is to be provided to operate the emergency release system (e.g. hold the brake open and allow release of the towline) in a dead-ship situation for a minimum of five minutes. This may be reduced to the time required for the full length of the towline to feed off the winch drum at the load specified in 3.1.5 if this is less than five minutes.

3.2 Operational requirements

3.2.1 Emergency release operation must be possible from the bridge and from the winch control station on deck. The winch control station on deck is to be in a safe location.

3.2.2 The emergency release control is to be located in close proximity to the emergency stop button for winch operation and both should be clearly identifiable, clearly visible, easily accessible and positioned to allow safe operability.

3.2.3 The emergency release function is to take priority over any emergency stop function. Activation of the winch emergency stop from any location is not to inhibit operation of the emergency release system from any location.

M79 (cont) 3.2.4 Emergency release system control buttons are to require positive action to cancel, the positive action may be made at a different control position from the one where the emergency release was activated. It must always be possible to cancel the emergency release from the bridge regardless of the activation location and without manual intervention on the working deck.

3.2.5 Controls for emergency use are to be protected against accidental use.

3.2.6 Indications are to be provided on the bridge for all power supply and/or pressure levels related to the normal operation of the emergency release system. Alarms are to activate automatically if any level falls outside of the limits within which the emergency release system is fully operational.

3.2.7 Wherever practicable, control of the emergency release system is to be provided by a hard-wired system, fully independent of programmable electronic systems.

3.2.8 Computer based systems that operate or may affect the control of emergency release systems are to meet the requirements for Category III systems of UR E22.

3.2.9 Components critical for the safe operation of the emergency release system are to be identified by the manufacturer.

3.2.10 The method for annual survey of the winch is to be documented.

3.2.11 Where necessary for conducting the annual survey of the winch, adequately sized strong points are to be provided on deck.

4 Test requirements

4.1 General

4.1.1 All testing defined within Section 4 is to be witnessed by a Classification Society surveyor.

4.1.2 For each emergency release system or type thereof, the performance requirements of Section 3.1 are to be verified either at the manufacturer's works or as part of the commissioning of the towing winch when it is installed on board. Where verification solely through testing is impracticable (e.g. due to health and safety), testing may be combined with inspection, analysis or demonstration in agreement with the Society.

4.1.3 The performance capabilities and operating instructions of the emergency release system are to be documented and made available on board the ship on which the winch has been installed.

4.2 Installation trials

4.2.1 The full functionality of the emergency release system is to be tested as part of the shipboard commissioning trials to the satisfaction of the surveyor. Testing may be conducted either during a bollard pull test or by applying the towline load against a strong point on the deck of the tug that is certified to the appropriate load.

4.2.2 Where the performance of the winch in accordance with Section 3.1 has previously been verified, the load applied for the installation trials is to be at least the lesser of 30% of the maximum design load or 80% of vessel bollard pull.

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